	Interface - EU67		
	Robot Out (Pin)	IMM In (Hole)	
26	Mold Area Safe C3	G2	11 ZA3
18	Mold Area Safe A3	V2	
20	Robot Enable B2	Safe Door	2
24	Core Pull In Enable B5	Safe Door ZC3	
23	Core Pull Out Enable B6	Mold Open Finish	3
32	IMM DC24V A9	Mold Open Finish ZA7	
		Mold Closed	
19	Emergency Stop Out A1	Mold Closed ZA6	12
27	Emergency Stop Out A1		
	Ejector Retreat Enable	Robot DC24V ZA9	16
21	Ejector Retreat Enable B3	Ejector Advance Stop ZB4	5
	Ejector Advance Enable	Ejector Retreat Stop ZB3	4
22	Ejector Advance Enable B4	Mold Intermediate Stop ZA8	
	Loop	Reject ZA5	8
	Loop	Fully Automatic ZB2	10
	Mold Open Enable	Core Pull In Stop ZB5	6
28	Mold Open Enable A7	Core Pull Out Stop ZB6	7
	Mold Close Enable	Emergency Stop In ZA1	9
17	Mold Close Enable A6	Emergency Stop In ZC1	1

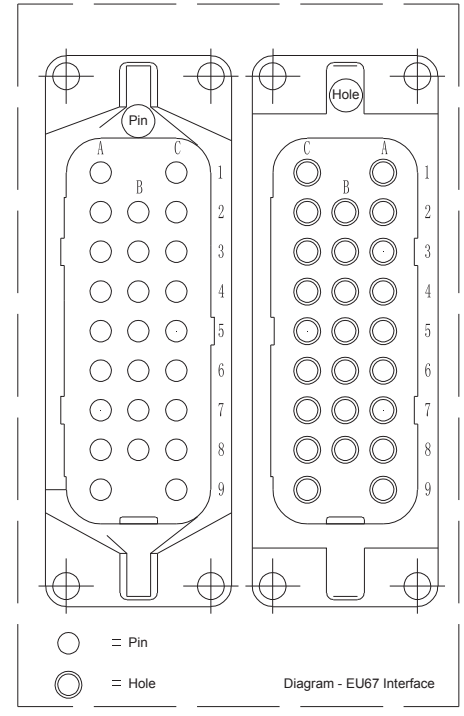

Diagram - EU67 Interface

Remarks:
1. Emergency Stop In 2 & Emergency Stop Out 2 Should be Provided Via Relay
2. The Input/Output Signal of Core 2 Could be Acquired via Short Circuit

Name	Drawing No.	Review	Date	Pages
Wiring - EU67 Interface	Power-SW6-0013	郑猛		13